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import socket

from threading import Thread

import json

import time

from encodings.punycode import Codec

class xpr_conn(Thread):

    id = ""

    timeoutInstalled = False

    def __init__(self, sock):

        Thread.__init__(self)

        self.conn = sock

        self.start()

    def __del__(self):

        self.conn.close()

        print("closed")

    def run(self):

        print("conn start")

        # получаем id

        data = self.conn.recv(1024)

        if not data: return

        self.id = data.decode("utf-8")
```

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if self.id != "xcontrol": return

while True:

    dic = {}

    if not self.timeoutInstalled:

        dic["__ss__"] = {"timeout_tcp": 10}

        self.timeoutInstalled = True

    else: time.sleep(5)

    self.conn.send(("@" + json.dumps(dic)).encode("utf-8"))

    # может быть таймаут, тогда будет ошибка

    try: data = self.conn.recv(1024)

    except: data = 0

    if not data: return

    data = data.decode("utf-8")

    # если не json, выходим

    try: dic = json.loads(data)

    except: return

    else: print(dic)
```